

**Emittance Exchange  
using thick Bent Solenoid elements**

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**Exchange Workshop  
BNL  
11 September 2000**

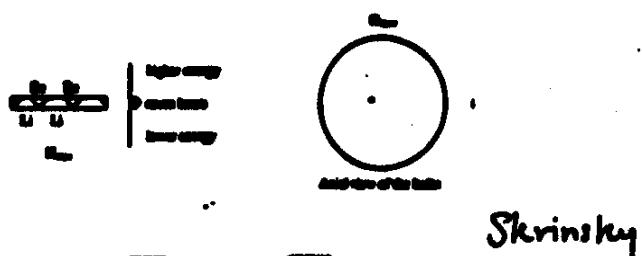
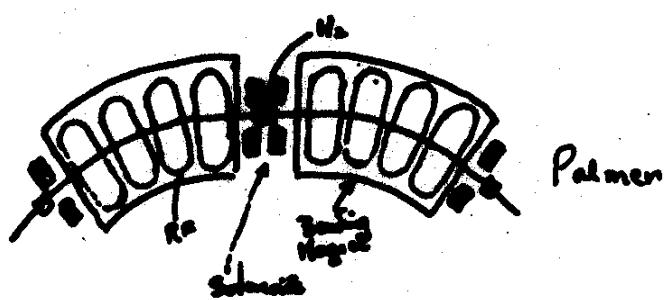
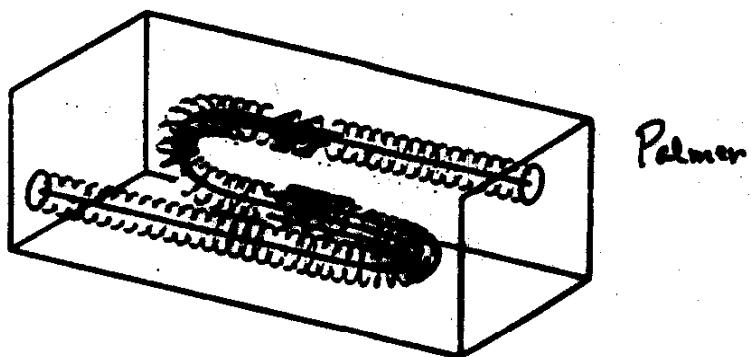
**Outline**

- 1. Bent solenoid dynamics**
- 2. Exchange design with rf**
- 3. Specific design**

## Emittance exchange

Methods of incorporating emittance exchange (EMEX) in cooling lattices

- standalone EMEX sections
- thin dispersive elements periodically in transverse cooling lattice
- conductor-absorber configuration for simultaneous transverse cooling plus EMEX



## **This study**

### **This study examines**

- standalone configuration
- thick bent solenoid elements

### **Goals for standalone EMEX system**

1. the momentum spread should be reduced by a factor of ~0.5
2. the bunch length should approximately equal that of the input beam
3. the transverse area should be symmetric and larger by a factor ~2
4. the transverse divergences should approximately equal that of the input beam
5. the mean momentum should approximately equal that of the input beam

### **Methods to describe bent solenoid fields**

- sum of individual current loops
- analytic fields (ICOOL)

1<sup>st</sup> order

2<sup>nd</sup> order

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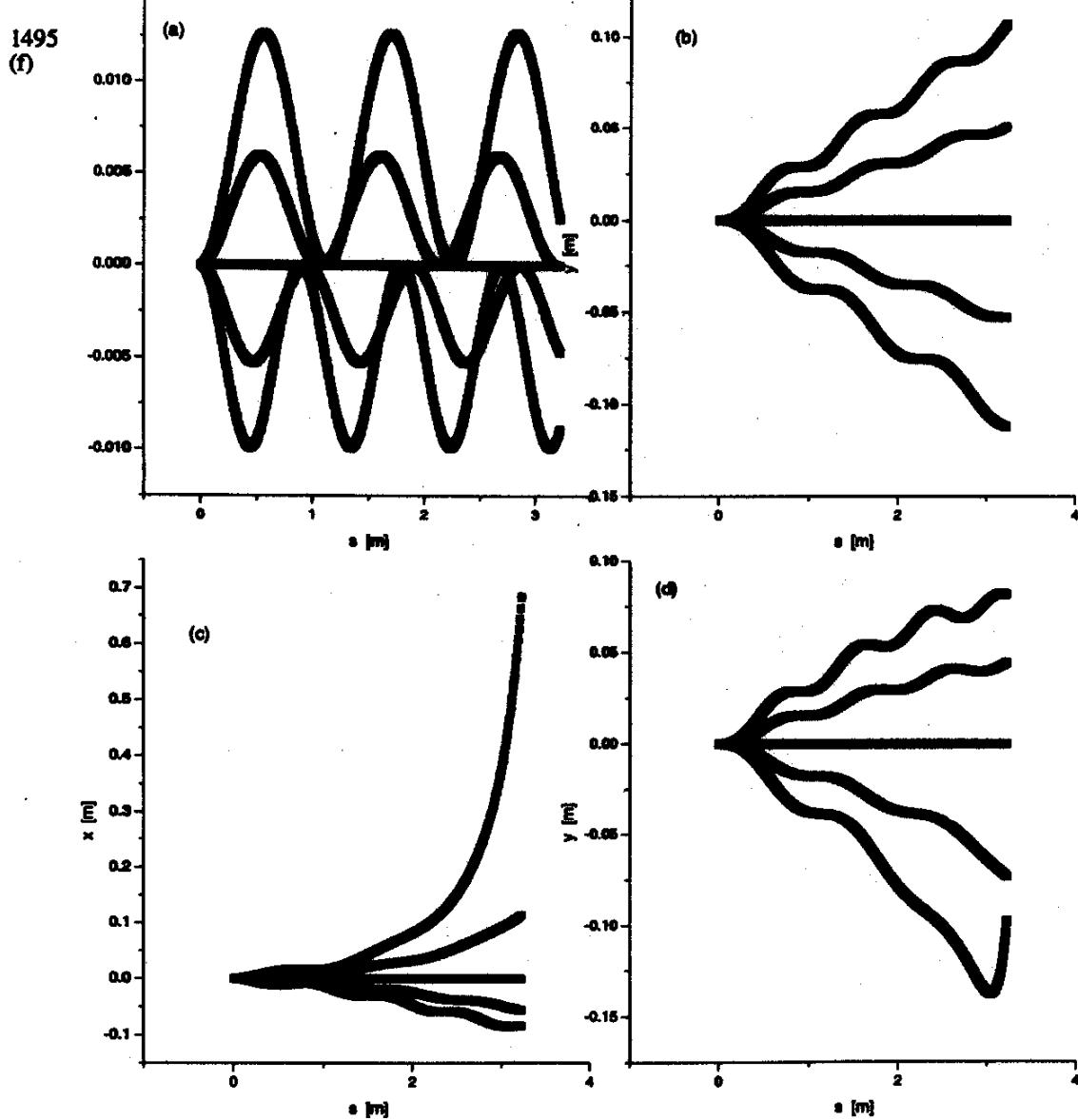


Figure 1. Particle orbits inside the bent solenoid field

|  $\underline{s^r}$  order

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$$L = 1 \lambda_L$$

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(e)

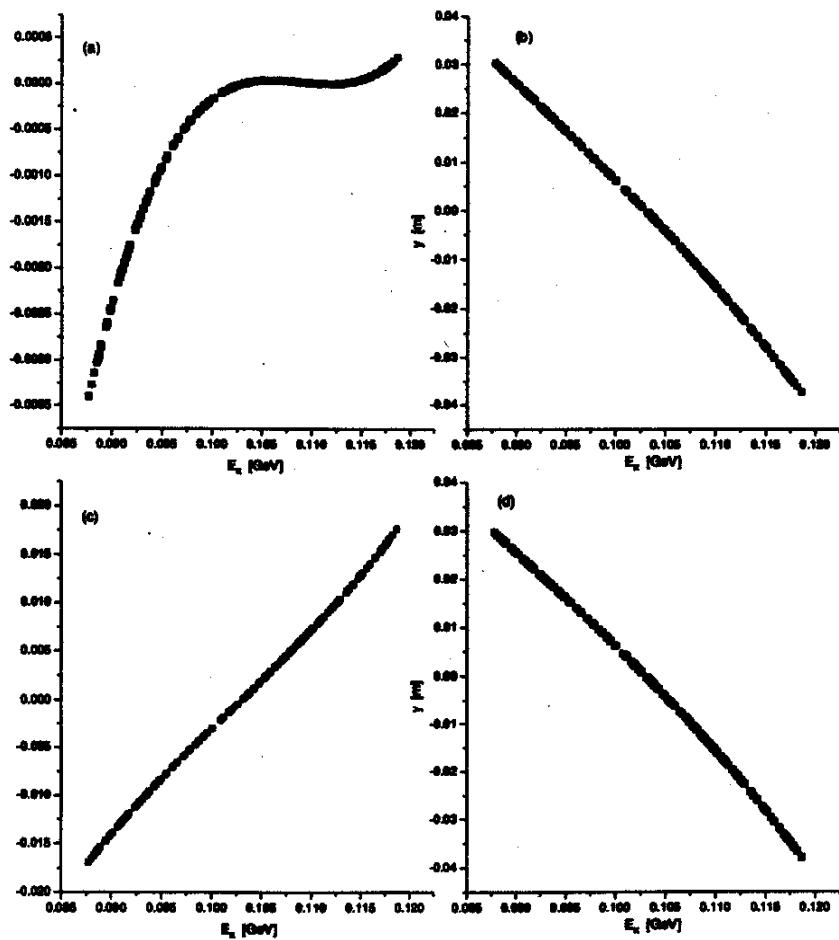
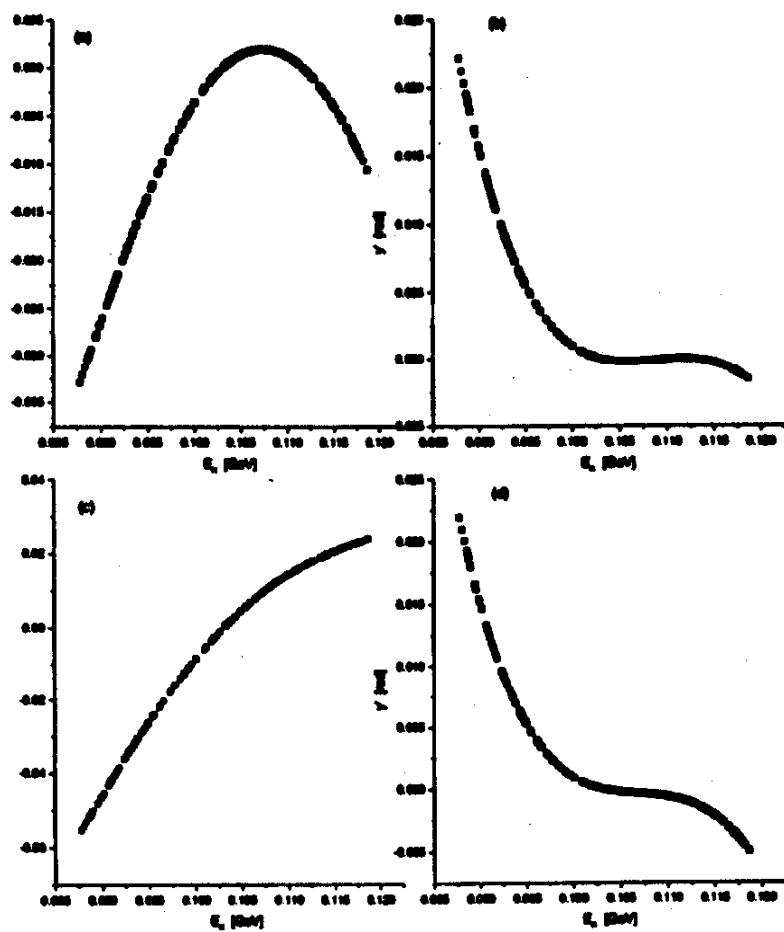


Figure 2. Dispersion for particles uniformly distribut

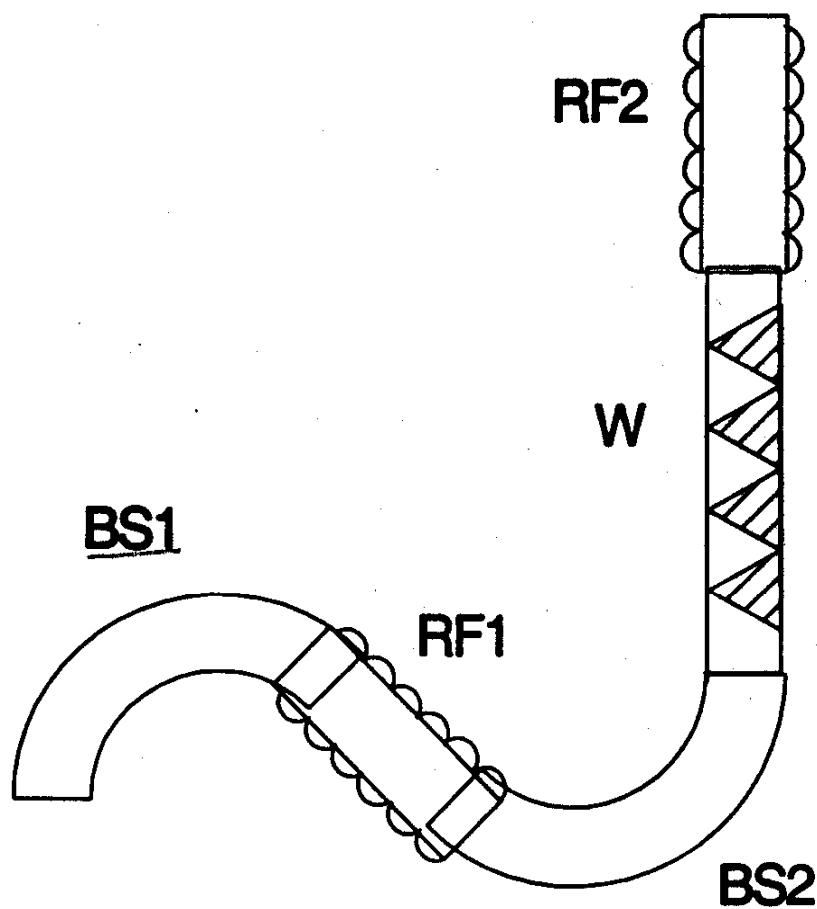
$$L = 1 \lambda_L$$



**Figure 3.** Angular dispersion for particles uniformly distributed between 162 and 198 MeV/c. (a)  $x'$  dispersion for uniform dipole field; (b)  $y'$  dispersion for uniform dipole field; (c)  $x'$  dispersion for field with quad component; (d)  $y'$  dispersion for field with quad component.

#### 4 Emittance exchange system design

We now consider the design of an actual emittance exchange system. The first half, dealing with dispersion in  $y$ , is shown schematically in Fig. 5.



**Figure 5.** Schematic layout of one half of an emittance exchange system.

Configuration  
 $P_z$  vs  $t$

## Bent solenoid fields

- vector potential [Wang & Chao; Morozov & Solov'ev]

$$\vec{A}(x, y, s) = -\frac{1}{2} B_{so}(s) \frac{y}{(1 + h(s)x)} \hat{x} + \frac{1}{2h(s)} B_{so}(s) \ln(1 + h(s)x) \hat{y}$$

- field components

$$\vec{B} = \nabla \times \vec{A}$$

- second order magnetic field components

$$B_x(x, y, s) = -\frac{1}{2} \left( B'_{so}(s)x - \frac{1}{2} B_{so}(s) h'(s)x^2 - \frac{3}{2} B'_{so}(s) h(s)x^2 \right)$$

$$B_y(x, y, s) = -\frac{1}{2} \left( B'_{so}(s)y - 2 B'_{so}(s) h(s)xy - B_{so}(s) h'(s)xy \right)$$

$$B_z(x, y, s) = (1 - h(s)x + h(s)^2 x^2) B_{so}(s)$$

- independent solenoid field component

$$B_{so}(s) = B_S \Delta \tanh(s; c, e, \lambda)$$

- $h(s)$  is the geometrical curvature

- assume  $\rho_{\text{geometry}} = \rho_{\text{dipole}}$

## Dipole field (second order)

$$B_x(x, y, s) = a_{11}(s)y + a_{12}(s)xy$$

$$B_y(x, y, s) = a_{10}(s) + a_{11}(s)x + \frac{1}{2}a_{12}(s)x^2 + \frac{1}{2}a_{30}(s)y^2$$

$$B_s(x, y, s) = a'_{10}(s)y + (a'_{11}(s) - h(s)a'_{10}(s))xy$$

- independent dipole and quadrupole components

$$a_{10}(s) = B_D \Delta \tanh(s; c_1, e_1, \lambda_1)$$

$$a_{11}(s) = B_Q \Delta \tanh(s; c_2, e_2, \lambda_2)$$

- sextupole constraints

$$a_{12}(s) = 2a''_{10}(s) + a'_{10}(s) \frac{h'(s)}{h(s)} + a_{11}(s)h(s) - \frac{1}{h(s)}a''_{11}(s)$$

$$a_{30}(s) = -a_{12}(s) - a_{11}(s)h(s) - a''_{10}(s)$$

- curvature

$$h(s) = \frac{q}{p_o} B_y(0, 0, s)$$

- satisfies Maxwell's equations to second order

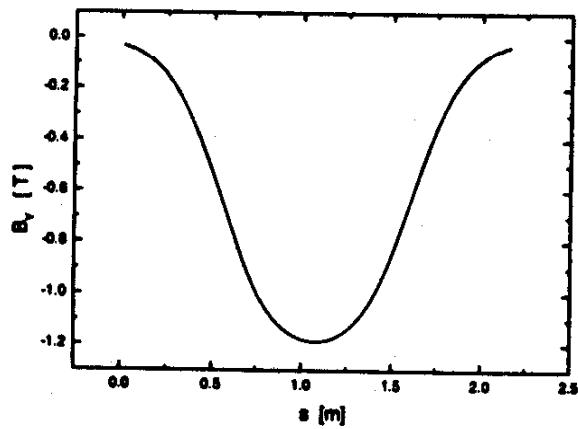
$$\nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{B} \approx 0$$

(error in  $a_{12}'$ )

**Table 2a Beam parameters**

	<b>Entrance</b>	
$p_0$	180	MeV/c
$\sigma_x$	21.1	mm
$\sigma_y$	21.2	mm
$\sigma_z$	20	mm
$\sigma_{px}$	14.9	MeV/c
$\sigma_{py}$	15.6	MeV/c
$\sigma_{pz}$	9.2	MeV/c
$\epsilon_{TN}$	2.08	mm
$\epsilon_{LN}$	1.68	mm
$\epsilon_{SN}$	7.1	mm <sup>3</sup>

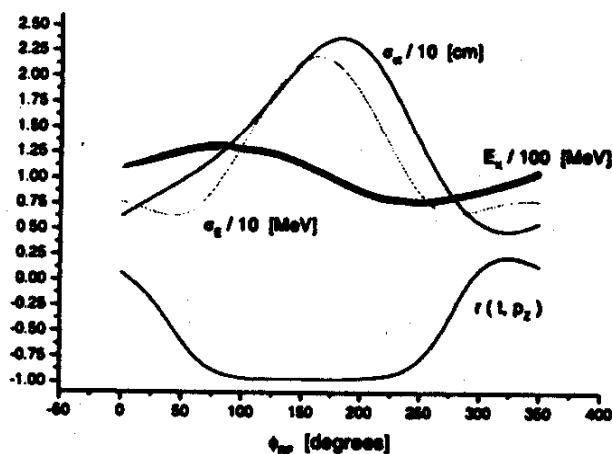


**Figure 6.** Dipole field profile for BS1.  $\approx -BS2$

Table 3 Bent solenoid parameters

$B_s$	3.5	T
$B_D$ (peak)	$\pm 1.19$	T
$g_Q$	0.	T / m
L	2.16	m
$\theta$	143	deg
$\rho$	0.5	m
$c_D$	1.06	m
$e_D$	0.55	m
$\lambda_D$	0.3	m

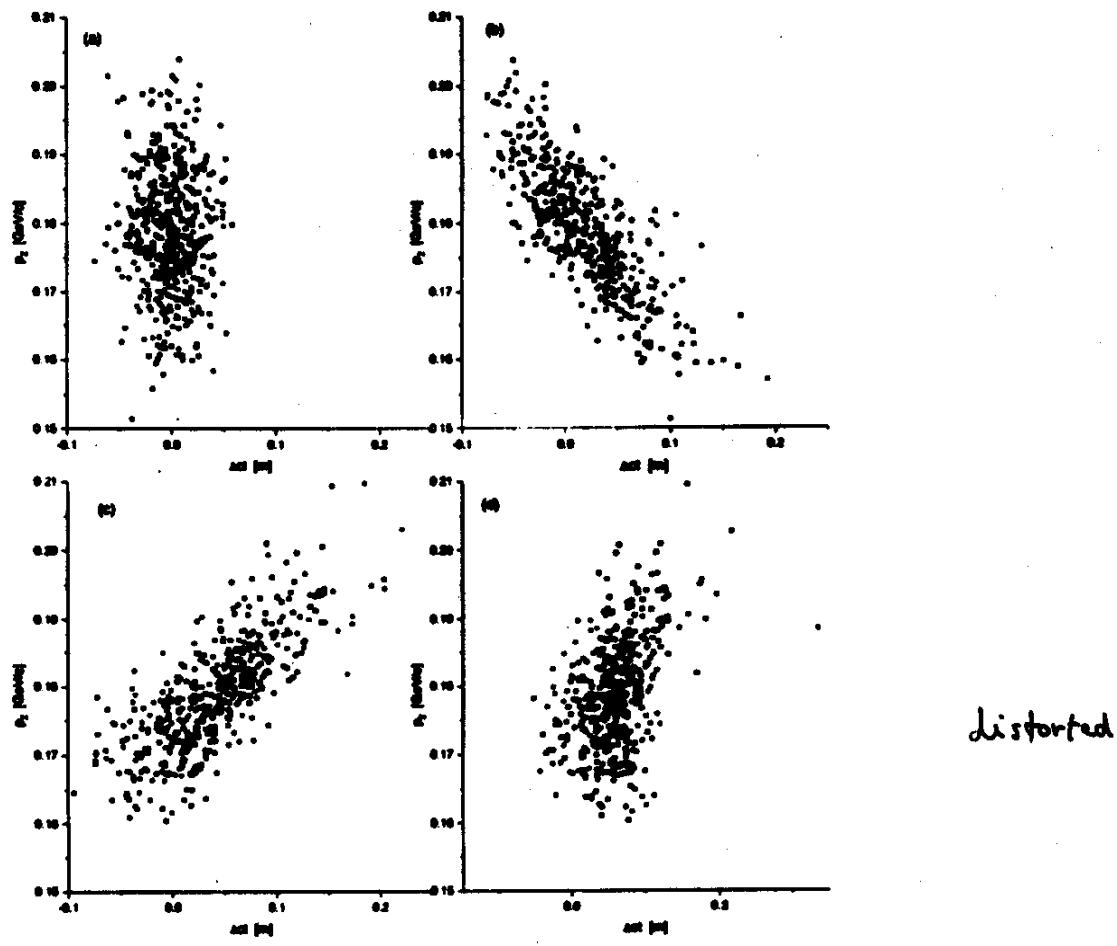
At end of BS2



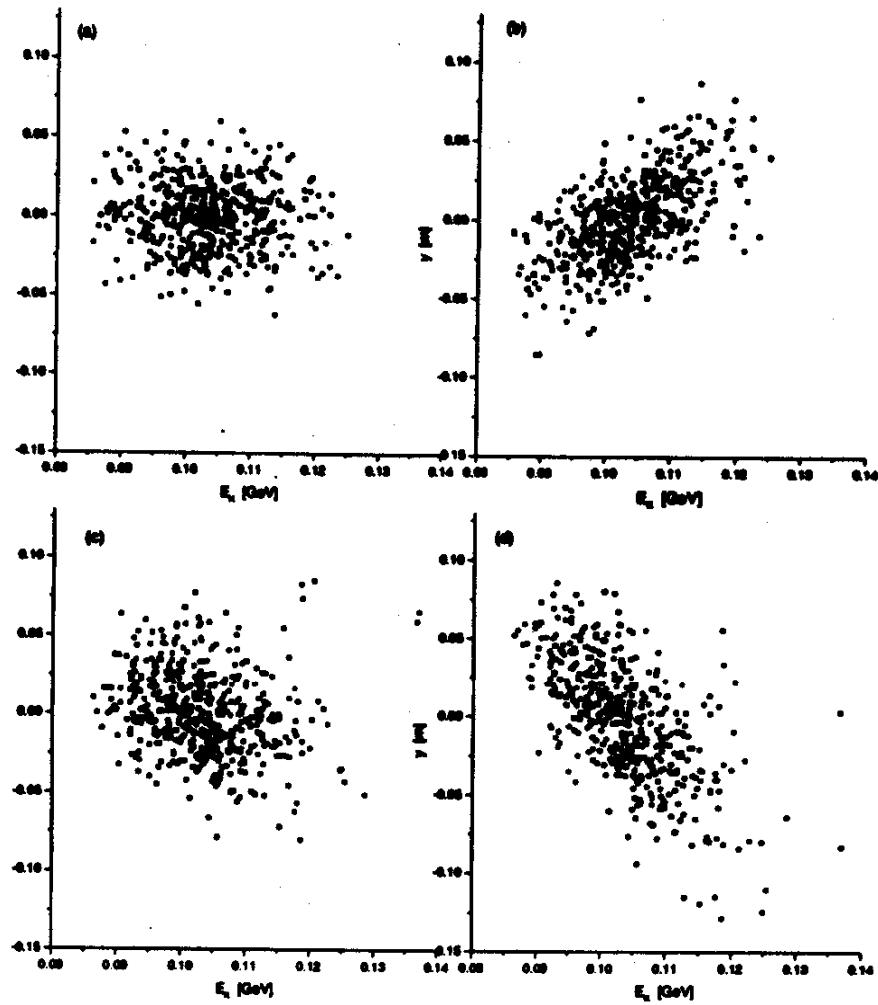
**Figure 7.** Dependence of average kinetic energy, energy spread, bunch length, and longitudinal phase space correlation on phase for RF1. The gradient is 17 MV/m.

Table 4 RF system design parameter

RF1	f	400	MHz
	G	17	MV / m
	$\Phi$	-14	deg
	$N_{cell}$	13	
	$L_{cell}$	16.62	cm
RF2	f	400	MHz
	G	12	MV / m
	$\Phi$	24	deg
	$N_{cell}$	13	
	$L_{cell}$	16.62	cm



**Figure 8.** Longitudinal phase space distribution,  $p_z$  vs  $ct$  (a) at production; (b) after BS1; (c) after RF1; (d) after BS2.



**Figure 9.** Dispersion distribution,  $y$  vs  $E_K$  (a) at production; (b) after BS1; (c) after RF1; (d) after BS2.

### 3.2 Wedge design

$$\begin{aligned}
 L_o &= \frac{f \Gamma}{n \left( \frac{dE}{dz} \right)} \\
 w &= 2D \frac{\Gamma}{P_o} \\
 h &= \pm 4\sigma_{ND} \\
 \tan \frac{\alpha}{2} &= \frac{L_o}{w} \\
 L_2 &= 2w \tan \frac{\alpha}{2} \leq L_{region}
 \end{aligned} \tag{1}$$

where  $f$  is the fraction of the momentum spread we want to remove,  $\Gamma$  is the full half-width of the momentum spread,  $n$  is the number of thin wedges we are using,  $\langle dE/dz \rangle$  is the average energy loss in the wedge material,  $D$  is the dispersion,  $w$  is the width along the dispersion direction,  $h$  is the width in the direction perpendicular to the dispersion, and  $\alpha$  is the full vertex angle.

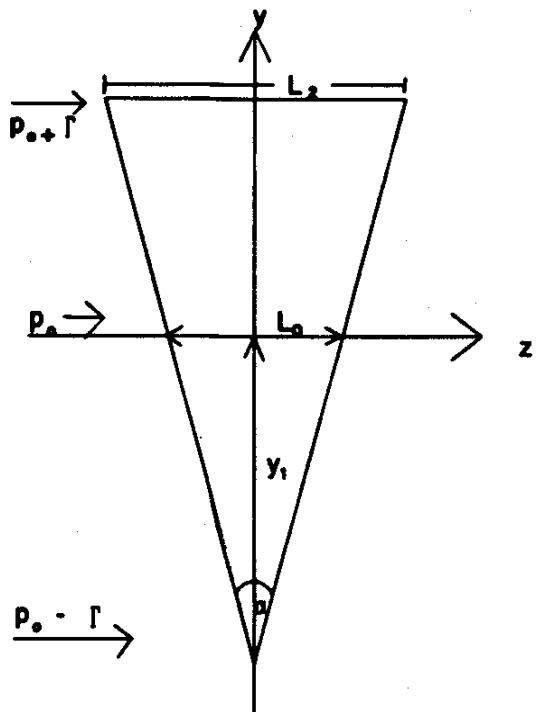


Figure 4. Linear wedge dimensions.

Table 5 Wedge design parameters

material	LiH	
$N_{wedges}$	4	
$L_{wedge}$	27	cm
$\alpha$	13	deg
$\varphi$	90	deg
w	22	cm
h	22	cm

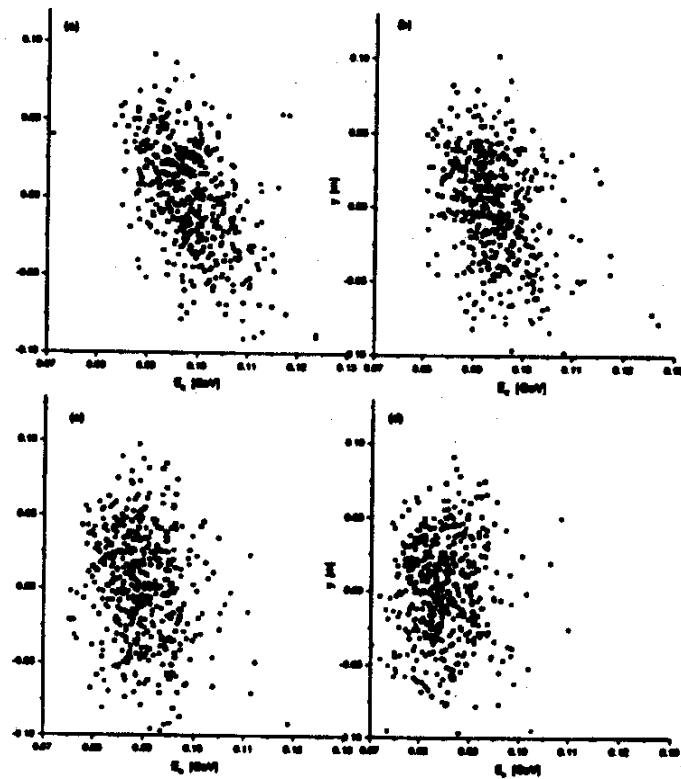
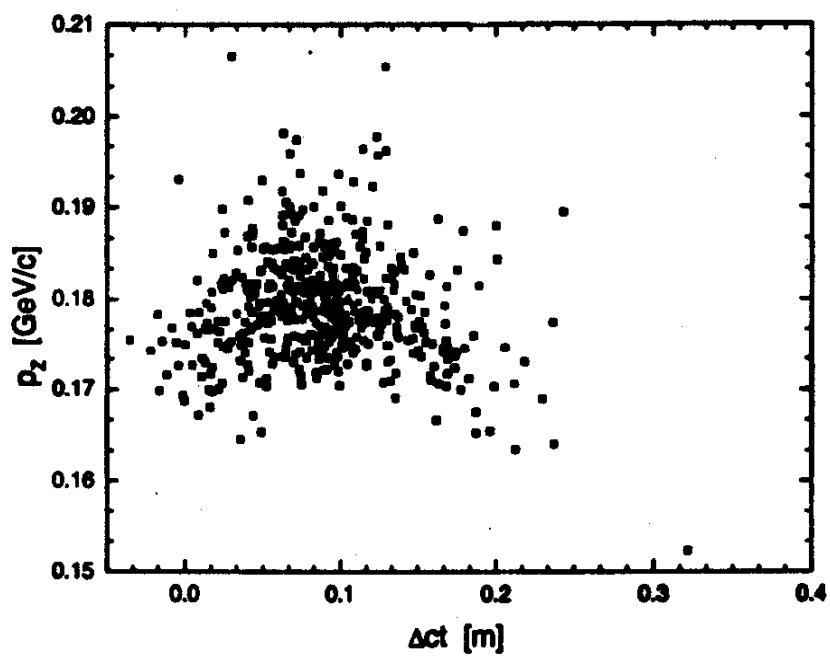


Figure 10. Dispersion distribution,  $y$  vs  $E_K$  (a) after wedge 1; (b) after wedge 2;  
(c) after wedge 3; (d) after wedge 4.



**Figure 11.** Longitudinal phase space distribution at the end of the (half) emittance exchange system.

$> \sqrt{2}$

Table 2 Beam parameters

	Entrance	Exit	
$p_0$	180	180	MeV/c
$\sigma_x$	21.1	19.1	mm
$\sigma_y$	21.2	36.4	mm
$\sigma_z$	20	68	mm
$\sigma_{px}$	14.9	13.8	MeV/c
$\sigma_{py}$	15.6	14.2	MeV/c
$\sigma_{pz}$	9.2	7.1	MeV/c
$\epsilon_{tn}$	2.08	2.79	mm
$\epsilon_{ln}$	1.68	2.17	mm
$\epsilon_{qn}$	7.1	14.8	mm <sup>3</sup>



Table 6 System performance

	Start	BS1	RF1	BS2	WED	RF2
$\langle KE \rangle$ [MeV]	103.2	103.2	103.1	103.1	84.9	103.3
$\sigma_{KE}$ [MeV]	7.76	7.76	7.83	7.83	6.47	6.44
$\sigma_\alpha$ [cm]	2.3	4.6	5.7	5.4	5.9	8.1
$r(x, KE)$	-0.03	0.01	0.02	0.01	0.21	0.19
$r(y, KE)$	-0.02	0.60	-0.17	-0.65	-0.09	-0.28
$r(t, p_z)$	-0.04	-0.80	0.58	0.17	-0.29	-0.44

## **Conclusions**

- no satisfactory solution found yet
- behaves roughly as expected, but no component works ideally
- complicated dynamics between bent solenoids and rf cavities
- error build-up limits performance
- huge parameter space to explore
- theoretical guidance would be helpful